GEOMETRY OF THE UNIT BALL IN VARIOUS HOLOMORPHIC SPACES Lecture 2

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• (This means that x is the only point of contact between a certain hyperplane and the ball.)

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- Now if $x = \frac{1}{2}(y + z)$ for some $y, z \in \text{ball}(X)$, then we have

$$1 = \phi(x) = \frac{1}{2} (\phi(y) + \phi(z)),$$

where $|\phi(y)| \leq 1$ and $|\phi(z)| \leq 1$.

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- Because 1 is an extreme point of $\overline{\mathbb{D}}$, we see that $\phi(y) = \phi(z) = 1$.
- And since x is an exposed point of ball (X), with exposing functional ϕ , it follows that y = z = x.

• Now suppose that (Ω, μ) is a measure space and X is a subspace of $L^1 = L^1(\Omega, \mu)$, endowed with the usual norm $\|f\|_1 := \int_{\Omega} |f| d\mu$.

Theorem

Let $f \in X$ be a function with $||f||_1 = 1$ satisfying $f \neq 0$ a.e. on Ω . TFAE: (i) f is an exposed point of ball (X). (ii) Whenever $h : \Omega \to [0, \infty)$ is a measurable function with $fh \in X$, we have h = const a.e. on Ω .

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• **Remarks.** (1) If $h \in L^{\infty}_{\mathbb{R}}$ and $fh \in X$, then $h_0 := h + ||h||_{\infty}$ satisfies $h_0 \ge 0$ and $fh_0 \in X$. Thus, condition (ii) is stronger (as it should be!) than its counterpart that arises for extreme points.

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- (2) Condition (ii) means that f is uniquely determined, among the unit-norm functions in X, by its argument f/|f|.

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- Now, if there is a nonconstant function h ≥ 0 with fh ∈ X, then g = fh/||fh||₁ is a unit-norm function in X, g ≠ f, and (*) holds.
- Conversely, if g is a unit-norm function in X, g ≠ f, making (*) true, then h = |g|/|f| is nonconstant and fh = g ∈ X.

• For subspaces of H^1 we also have:

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• Here, N⁺ is the Smirnov class, i.e.,

$$N^+ = \{ u/v : u, v \in H^{\infty}, v \text{ outer} \}.$$

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- Indeed, if $fh(=:g) \in H^1$ for some function $h \ge 0$, then $h = g \cdot \frac{1}{f} \in H^{1/2}$. Since positive $H^{1/2}$ functions are constants, we have h = const.

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- A simple necessary condition: If $f \in H^1$ is a unit-norm function of the form $f = (1 + J)^2 F$, with J inner and F outer, then f is not exposed.
- Indeed, letting $h = -\left(\frac{1-J}{1+J}\right)^2$, we get $fh = -(1-J)^2 F \in H^1$. (Note that $h \ge 0$.)

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- This can be viewed as a special case of the Toeplitz kernel

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- Namely, for $\varphi = \overline{z}^{N+1}$, we have $K_1(\varphi) = \mathcal{P}_N$.
- The map $f \mapsto \overline{z\varphi f}(=:\widetilde{f})$ reduces then to the following.

$$p^*(z) := z^N \overline{p\left(1/\overline{z}
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- The zeros of *p* and *p*^{*} being symmetric with respect to T, this last condition can be stated in terms of *p* alone.

In fact, we have

Theorem 1 (K.D., 2000)

Suppose $p \in \mathcal{P}_N$ and $\|p\|_1 = 1$.

(A) Then p is an extreme point of $ball(\mathcal{P}_N)$ if and only if the following conditions hold:

(i) $|\hat{p}(0)| + |\hat{p}(N)| \neq 0$; (ii) *p* has no pair of symmetric zeros w. r. t. \mathbb{T} .

(B) Furthermore, p is an exposed point of ball (\mathcal{P}_N) if and only if it satisfies (i), (ii) and (iii) p has no multiple zeros on \mathbb{T} .

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- What happens if we move from $\mathbb T$ to $\mathbb R?$
- With a function $f \in L^1(\mathbb{R})$ we associate its *Fourier transform*

$$\widehat{f}(\xi) := \int_{\mathbb{R}} e^{-ix\xi} f(x) \, dx, \qquad \xi \in \mathbb{R},$$

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• Finally, given $\sigma > 0$, we define the *Paley–Wiener space* PW_{σ}^{1} by

$$PW_{\sigma}^{1} := \{ f \in L^{1}(\mathbb{R}) : \operatorname{spec} f \subset [-\sigma, \sigma] \}.$$

• The nonperiodic counterpart of Theorem 1 is:

Theorem 2 (K.D., 2000)

Let $\sigma > 0$. Suppose $f \in PW_{\sigma}^1$ and $||f||_1 = 1$.

(A) Then f is an extreme point of ball (PW_{σ}^{1}) if and only if the following conditions hold:

- (i) At least one of the points $\pm \sigma$ is in spec *f*;
- (ii) f has no pair of symmetric zeros w. r. t. \mathbb{R} .

(B) Furthermore, f is an exposed point of ball (PW_{σ}^{1}) if and only if it satisfies (i), (ii), as well as

(iii) f has no multiple zeros on \mathbb{R} ;

(iv) $\int_{\mathbb{R}} |f(x)|h(x)dx = \infty$ whenever h is a nonconstant entire function of exponential type 0 that satisfies $h \ge 0$ on \mathbb{R} .

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- What are the extreme/exposed points of $ball(PW_S^1)$?
- Here, a first step was made by A. Ulanovskii and I. Zlotnikov who studied the case of

$$S = [-\sigma, -\rho] \cup [\rho, \sigma], \quad 0 < \rho < \sigma.$$

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• Going back to \mathbb{T} : the space $\mathcal{P}(\Lambda)$ of "fewnomials" with spectrum in an (arbitrary) finite set $\Lambda \subset \mathbb{Z}_+$ has been studied, and the two types of points in ball $(\mathcal{P}(\Lambda))$ have been characterized.

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• Consider the *punctured Hardy space*

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• **Problem:** Characterize (at least) the extreme points of $ball(H^1_{\mathcal{K}})$.

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- That is, I is writable (possibly after multiplication by a unimodular constant) as

$$I(z) = \prod_{j=1}^m \frac{z-a_j}{1-\overline{a}_j z},$$

where $0 \leq m \leq M$ and $a_1, \ldots, a_m \in \mathbb{D}$.

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• In addition, there is an interplay between the two factors, *I* and *F*, which we now describe.

• Consider the (outer) function

$$F_0(z) := F(z) \prod_{j=1}^m (1 - \overline{a}_j z)^{-2}$$

and its coefficients

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• Note that $F_0 \in H^1$ and so $C_k = 0$ for all k < 0. Put

 $A(k) := \operatorname{Re} C_k, \qquad B(k) := \operatorname{Im} C_k \qquad (k \in \mathbb{Z}).$

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Punctured H^1 : results

• Now define, for $j = 1, \ldots, M$ and $\ell = 0, \ldots, m$, the numbers

$$egin{aligned} &A_{j,\ell}^+ := A(k_j + \ell - m) + A(k_j - \ell - m), & B_{j,\ell}^+ := B(k_j + \ell - m) + B(k_j - \ell - m), \ &A_{j,\ell}^- := A(k_j + \ell - m) - A(k_j - \ell - m), & B_{j,\ell}^- := B(k_j + \ell - m) - B(k_j - \ell - m). \end{aligned}$$

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• From these, we build the $M \times (m+1)$ matrices

$$\mathcal{A}^+ := \left\{ \mathcal{A}_{j,\ell}^+ \right\}, \qquad \mathcal{B}^+ := \left\{ \mathcal{B}_{j,\ell}^+ \right\}$$

and the M imes m matrices (with j as above and $\ell = 1, \dots, m$)

$$\mathcal{A}^- := \left\{ \mathcal{A}^-_{j,\ell} \right\}, \qquad \mathcal{B}^- := \left\{ \mathcal{B}^-_{j,\ell} \right\}.$$

Punctured *H*¹: results

• Finally, we need the block matrix

$$\mathfrak{M} = \mathfrak{M}_{\mathcal{K}}\left(\mathsf{F}, \{\mathsf{a}_j\}_{j=1}^m\right) := \begin{pmatrix} \mathcal{A}^+ & \mathcal{B}^-\\ \mathcal{B}^+ & -\mathcal{A}^- \end{pmatrix},$$

which has 2M rows and 2m + 1 columns.

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• Our main result now says:

Theorem

Suppose that $f \in H^1_{\mathcal{K}}$ and $||f||_1 = 1$. Assume further that f = IF, where I is inner and F is outer. Then f is an extreme point of $\operatorname{ball}(H^1_{\mathcal{K}})$ if and only if the following two conditions hold: (a) I is a finite Blaschke product whose degree, say m, does not exceed M. (b) The matrix $\mathfrak{M} = \mathfrak{M}_{\mathcal{K}}(F, \{a_j\}_{j=1}^m)$, built as above from F and the zeros $\{a_j\}_{i=1}^m$ of I, has rank 2m.

Punctured *H*¹: results

• **Example:** Suppose that $\mathcal{K} = \{k\}$, where $k \in \mathbb{N}$ and $k \ge 2$. Let $F \in H^1$ be an outer function with $||F||_1 = 1$ and $\widehat{F}(k-1) = 0$; then put f(z) := zF(z). Applying the theorem, we get:

f is an extreme point of $\operatorname{ball}(H^1_{\{k\}}) \iff |\widehat{F}(k-2)| \neq |\widehat{F}(k)|.$

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What about exposed points in H¹_K? Here is a simple sufficient condition (for a general finite set K ⊂ N):

Proposition

If f is an extreme point of $\operatorname{ball}(H^1_{\mathcal{K}})$ and if $1/f \in L^1$, then f is an exposed point of $\operatorname{ball}(H^1_{\mathcal{K}})$.

• The proof of the theorem relies on two lemmas.

Lemma 1

Let X be a subspace of H^1 . Suppose that $f \in X$ is a function with $||f||_1 = 1$ whose canonical factorization is f = IF, with I inner and F outer. The following conditions are equivalent: (i) f is an extreme point of ball(X). (ii) Whenever $h \in L^{\infty}_{\mathbb{R}}$ and $fh \in X$, we have h = const.(iii) Whenever $G \in H^{\infty}$ is a function satisfying $G/I \in L^{\infty}_{\mathbb{R}}$ and $FG \in X$, we have G = cI for some $c \in \mathbb{R}$.

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• This will be applied with $X = H^1_{\mathcal{K}}$.

• **Definition:** Given a nonnegative integer N and a polynomial p, we say that p is N-symmetric if $\overline{z}^N p(z) \in \mathbb{R}$ for all $z \in \mathbb{T}$.

Two lemmas

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- Equivalently, a polynomial p is N-symmetric if (and only if)

$$\widehat{p}(N-k) = \overline{\widehat{p}(N+k)}$$

for all $k \in \mathbb{Z}$.

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• The general form of such a polynomial is

$$p(z) = \sum_{k=0}^{N-1} (\alpha_{N-k} - i\beta_{N-k}) z^k + 2\alpha_0 z^N + \sum_{k=N+1}^{2N} (\alpha_{k-N} + i\beta_{k-N}) z^k,$$

where $\alpha_0, \ldots, \alpha_N$ and β_1, \ldots, β_N are real parameters.

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• We may therefore identify p with its coefficient vector

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• We may therefore identify *p* with its *coefficient vector*

```
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```

• Now comes

Lemma 2

Given $N \in \mathbb{Z}_+$ and points $a_1, \ldots, a_N \in \mathbb{D}$, let

$$B(z) := \prod_{j=1}^{N} rac{z-a_j}{1-\overline{a}_j z}.$$

The general form of a function $G \in H^{\infty}$ satisfying $G/B \in L^{\infty}_{\mathbb{R}}$ is then $G(z) := p(z) \prod_{j=1}^{N} (1 - \overline{a}_j z)^{-2}$, where p is an N-symmetric polynomial.

Last slide

To be continued...